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### ***Rocky Enterprise Linux 9.2 Manual Pages on command 'sem\_post.3'***

**\$ man sem\_post.3**

SEM\_POST(3)                      Linux Programmer's Manual                      SEM\_POST(3)

#### **NAME**

sem\_post - unlock a semaphore

#### **SYNOPSIS**

```
#include <semaphore.h>

int sem_post(sem_t *sem);

Link with -pthread.
```

#### **DESCRIPTION**

sem\_post() increments (unlocks) the semaphore pointed to by sem. If the semaphore's value consequently becomes greater than zero, then another process or thread blocked in a sem\_wait(3) call will be woken up and proceed to lock the semaphore.

#### **RETURN VALUE**

sem\_post() returns 0 on success; on error, the value of the semaphore is left unchanged, -1 is returned, and errno is set to indicate the error.

#### **ERRORS**

EINVAL sem is not a valid semaphore.

#### **E\_OVERFLOW**

The maximum allowable value for a semaphore would be exceeded.

#### **ATTRIBUTES**

For an explanation of the terms used in this section, see attributes(7).

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?Interface ? Attribute ? Value ?

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?sem\_post() ? Thread safety ? MT-Safe ?

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## CONFORMING TO

POSIX.1-2001.

## NOTES

sem\_post() is async-signal-safe: it may be safely called within a signal handler.

## EXAMPLES

See sem\_wait(3) and shm\_open(3).

## SEE ALSO

sem\_getvalue(3), sem\_wait(3), sem\_overview(7), signal-safety(7)

## COLOPHON

This page is part of release 5.10 of the Linux man-pages project. A description of the project, information about reporting bugs, and the latest version of this page, can be found at <https://www.kernel.org/doc/man-pages/>.

Linux

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