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Red Hat Enterprise Linux Release 9.2 Manual Pages on 'ioctl.3p' command

\$ man ioctl.3p

IOCTL(3P) POSIX Programmer's Manual IOCTL(3P)

PROLOG

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NAME

ioctl ? control a STREAMS device (STREAMS)

SYNOPSIS

```
#include <stropts.h>

int ioctl(int fildes, int request, ... /* arg */);
```

DESCRIPTION

The `ioctl()` function shall perform a variety of control functions on STREAMS devices. For non-STREAMS devices, the functions performed by this call are unspecified. The request argument and an optional third argument (with varying type) shall be passed to and interpreted by the appropriate part of the STREAM associated with fildes.

The fildes argument is an open file descriptor that refers to a device.

The request argument selects the control function to be performed and shall depend on the STREAMS device being addressed.

The arg argument represents additional information that is needed by this specific STREAMS device to perform the requested function. The type of arg depends upon the particular control request, but it shall

be either an integer or a pointer to a device-specific data structure.

The `ioctl()` commands applicable to STREAMS, their arguments, and error conditions that apply to each individual command are described below.

The following `ioctl()` commands, with error values indicated, are applicable to all STREAMS files:

I_PUSH Pushes the module whose name is pointed to by `arg` onto the top of the current STREAM, just below the STREAM head. It then calls the `open()` function of the newly-pushed module.

The `ioctl()` function with the `I_PUSH` command shall fail if:

EINVAL Invalid module name.

ENXIO Open function of new module failed.

ENXIO Hangup received on `fildev`.

I_POP Removes the module just below the STREAM head of the STREAM pointed to by `fildev`. The `arg` argument should be 0 in an `I_POP` request.

The `ioctl()` function with the `I_POP` command shall fail if:

EINVAL No module present in the STREAM.

ENXIO Hangup received on `fildev`.

I_LOOK Retrieves the name of the module just below the STREAM head of the STREAM pointed to by `fildev`, and places it in a character string pointed to by `arg`. The buffer pointed to by `arg` should be at least `FMNAMESZ+1` bytes long, where `FMNAMESZ` is defined in `<stropts.h>`.

The `ioctl()` function with the `I_LOOK` command shall fail if:

EINVAL No module present in the STREAM.

I_FLUSH Flushes read and/or write queues, depending on the value of `arg`. Valid `arg` values are:

FLUSHR Flush all read queues.

FLUSHW Flush all write queues.

FLUSHRW Flush all read and all write queues.

The `ioctl()` function with the `I_FLUSH` command shall fail if:

EINVAL Invalid `arg` value.

EAGAIN or ENOSR

Unable to allocate buffers for flush message.

ENXIO Hangup received on fildes.

I_FLUSHBAND Flushes a particular band of messages. The arg argument points to a bandinfo structure. The bi_flag member may be one of FLUSHR, FLUSHW, or FLUSHRW as described above. The bi_pri member determines the priority band to be flushed.

I_SETSIG Requests that the STREAMS implementation send the SIGPOLL signal to the calling process when a particular event has occurred on the STREAM associated with fildes. I_SETSIG supports an asynchronous processing capability in STREAMS. The value of arg is a bitmask that specifies the events for which the process should be signaled. It is the bitwise-inclusive OR of any combination of the following constants:

S_RDNORM A normal (priority band set to 0) message has arrived at the head of a STREAM head read queue. A signal shall be generated even if the message is of zero length.

S_RDBAND A message with a non-zero priority band has arrived at the head of a STREAM head read queue. A signal shall be generated even if the message is of zero length.

S_INPUT A message, other than a high-priority message, has arrived at the head of a STREAM head read queue. A signal shall be generated even if the message is of zero length.

S_HIPRI A high-priority message is present on a STREAM head read queue. A signal shall be generated even if the message is of zero length.

S_OUTPUT The write queue for normal data (priority band 0) just below the STREAM head is no longer full. This notifies the process that there is room on the queue for sending (or writing) nor?

mal data downstream.

S_WRNORM Equivalent to **S_OUTPUT**.

S_WRBAND The write queue for a non-zero priority band just below the **STREAM** head is no longer full.

This notifies the process that there is room on the queue for sending (or writing) priority data downstream.

S_MSG A **STREAMS** signal message that contains the **SIG?** **POLL** signal has reached the front of the **STREAM** head read queue.

S_ERROR Notification of an error condition has reached the **STREAM** head.

S_HANGUP Notification of a hangup has reached the **STREAM** head.

S_BANDURG When used in conjunction with **S_RDBAND**, **SIGURG** is generated instead of **SIGPOLL** when a priority message reaches the front of the **STREAM** head read queue.

If **arg** is 0, the calling process shall be unregistered and shall not receive further **SIGPOLL** signals for the stream associated with **fd**.

Processes that wish to receive **SIGPOLL** signals shall ensure that they explicitly register to receive them using **I_SET?**

SIG. If several processes register to receive this signal for the same event on the same **STREAM**, each process shall be signaled when the event occurs.

The **ioctl()** function with the **I_SETSIG** command shall fail if:

EINVAL The value of **arg** is invalid.

EINVAL The value of **arg** is 0 and the calling process is not registered to receive the **SIGPOLL** signal.

EAGAIN There were insufficient resources to store the **sig?** **nal** request.

I_GETSIG Returns the events for which the calling process is currently registered to be sent a SIGPOLL signal. The events are returned as a bitmask in an `int` pointed to by `arg`, where the events are those specified in the description of **I_SETSIG** above.

The `ioctl()` function with the **I_GETSIG** command shall fail if:

EINVAL Process is not registered to receive the SIGPOLL signal.

I_FIND Compares the names of all modules currently present in the **STREAM** to the name pointed to by `arg`, and returns 1 if the named module is present in the **STREAM**, or returns 0 if the named module is not present.

The `ioctl()` function with the **I_FIND** command shall fail if:

EINVAL `arg` does not contain a valid module name.

I_PEEK Retrieves the information in the first message on the **STREAM** head read queue without taking the message off the queue. It is analogous to `getmsg()` except that this command does not remove the message from the queue. The `arg` argument points to a `strpeek` structure.

The application shall ensure that the `maxlen` member in the `ctlbuf` and `databuf` `strbuf` structures is set to the number of bytes of control information and/or data information, respectively, to retrieve. The `flags` member may be marked **RS_HIPRI** or 0, as described by `getmsg()`. If the process sets `flags` to **RS_HIPRI**, for example, **I_PEEK** shall only look for a high-priority message on the **STREAM** head read queue.

I_PEEK returns 1 if a message was retrieved, and returns 0 if no message was found on the **STREAM** head read queue, or if the **RS_HIPRI** flag was set in `flags` and a high-priority message was not present on the **STREAM** head read queue. It does not wait for a message to arrive. On return, `ctlbuf` specifies information in the control buffer, `databuf` speci?

fies information in the data buffer, and flags contains the value RS_HIPRI or 0.

I_SRDOPT Sets the read mode using the value of the argument `arg`.

Read modes are described in `read()`. Valid `arg` flags are:

RNORM Byte-stream mode, the default.

RMSGD Message-discard mode.

RMSGN Message-nondiscard mode.

The bitwise-inclusive OR of **RMSGD** and **RMSGN** shall return `[EINVAL]`. The bitwise-inclusive OR of **RNORM** and either **RMSGD** or **RMSGN** shall result in the other flag overriding **RNORM** which is the default.

In addition, treatment of control messages by the **STREAM** head may be changed by setting any of the following flags in `arg`:

RPROTNORM Fail `read()` with `[EBADMSG]` if a message containing a control part is at the front of the **STREAM** head read queue.

RPROTDAT Deliver the control part of a message as data when a process issues a `read()`.

RPROTDIS Discard the control part of a message, delivering any data portion, when a process issues a `read()`.

The `ioctl()` function with the **I_SRDOPT** command shall fail if:

EINVAL The `arg` argument is not valid.

I_GRDOPT Returns the current read mode setting, as described above, in an `int` pointed to by the argument `arg`. Read modes are described in `read()`.

I_NREAD Counts the number of data bytes in the data part of the first message on the **STREAM** head read queue and places this value in the `int` pointed to by `arg`. The return value for the command shall be the number of messages on the **STREAM** head read queue. For example, if 0 is returned in `arg`, but

the `ioctl()` return value is greater than 0, this indicates that a zero-length message is next on the queue.

`I_FDINSERT` Creates a message from specified buffer(s), adds information about another STREAM, and sends the message down? stream. The message contains a control part and an optional data part. The data and control parts to be sent are distinguished by placement in separate buffers, as described below. The `arg` argument points to a `strfdinsert` structure. The application shall ensure that the `len` member in the `ctlbuf` `strbuf` structure is set to the size of a `t_uscalar_t` plus the number of bytes of control information to be sent with the message. The `files` member specifies the file descriptor of the other STREAM, and the `offset` member, which must be suitably aligned for use as a `t_uscalar_t`, specifies the offset from the start of the control buffer where `I_FDINSERT` shall store a `t_uscalar_t` whose interpretation is specific to the STREAM end. The application shall ensure that the `len` member in the `databuf` `strbuf` structure is set to the number of bytes of data information to be sent with the message, or to 0 if no data part is to be sent. The `flags` member specifies the type of message to be created. A normal message is created if `flags` is set to 0, and a high-priority message is created if `flags` is set to `RS_HIPRI`. For non-priority messages, `I_FDINSERT` shall block if the STREAM write queue is full due to internal flow control conditions. For priority messages, `I_FDINSERT` does not block on this condition. For non-priority messages, `I_FDINSERT` does not block when the write queue is full and `O_NONBLOCK` is set. Instead, it fails and sets `errno` to `[EAGAIN]`. `I_FDINSERT` also blocks, unless prevented by lack of internal resources, waiting for the availability of message blocks in the STREAM, regardless of priority or whether

O_NONBLOCK has been specified. No partial message is sent.

The ioctl() function with the I_FDINSERT command shall fail

if:

EAGAIN A non-priority message is specified, the O_NONBLOCK

flag is set, and the STREAM write queue is full due

to internal flow control conditions.

EAGAIN or ENOSR

Buffers cannot be allocated for the message that is

to be created.

EINVAL One of the following:

- The fildes member of the strfdinsert structure is not a valid, open STREAM file descriptor.
- The size of a t_uscalar_t plus offset is greater than the len member for the buffer specified through ctlbuf.
- The offset member does not specify a properly-aligned location in the data buffer.
- An undefined value is stored in flags.

ENXIO Hangup received on the STREAM identified by either

the fildes argument or the fildes member of the

strfdinsert structure.

ERANGE The len member for the buffer specified through

databuf does not fall within the range specified by

the maximum and minimum packet sizes of the topmost

STREAM module; or the len member for the buffer

specified through databuf is larger than the maximum

configured size of the data part of a message; or

the len member for the buffer specified through ctl?

buf is larger than the maximum configured size of

the control part of a message.

I_STR Constructs an internal STREAMS ioctl() message from the

data pointed to by arg, and sends that message downstream.

This mechanism is provided to send `ioctl()` requests to downstream modules and drivers. It allows information to be sent with `ioctl()`, and returns to the process any information sent upstream by the downstream recipient. `I_STR` shall block until the system responds with either a positive or negative acknowledgement message, or until the request times out after some period of time. If the request times out, it shall fail with `errno` set to `[ETIME]`.

At most, one `I_STR` can be active on a `STREAM`. Further `I_STR` calls shall block until the active `I_STR` completes at the `STREAM` head. The default timeout interval for these requests is 15 seconds. The `O_NONBLOCK` flag has no effect on this call.

To send requests downstream, the application shall ensure that `arg` points to a `strioc_t` structure.

The `ic_cmd` member is the internal `ioctl()` command intended for a downstream module or driver and `ic_timeout` is the number of seconds (-1=infinite, 0=use implementation-defined timeout interval, >0=as specified) an `I_STR` request shall wait for acknowledgement before timing out. `ic_len` is the number of bytes in the data argument, and `ic_dp` is a pointer to the data argument. The `ic_len` member has two uses: on input, it contains the length of the data argument passed in, and on return from the command, it contains the number of bytes being returned to the process (the buffer pointed to by `ic_dp` should be large enough to contain the maximum amount of data that any module or the driver in the `STREAM` can return).

The `STREAM` head shall convert the information pointed to by the `strioc_t` structure to an internal `ioctl()` command message and send it downstream.

The `ioctl()` function with the `I_STR` command shall fail if:

`EAGAIN` or `ENOSR`

Unable to allocate buffers for the `ioctl()` message.

`EINVAL` The `ic_len` member is less than 0 or larger than the maximum configured size of the data part of a message, or `ic_timeout` is less than -1.

`ENXIO` Hangup received on fildes.

`ETIME` A downstream `ioctl()` timed out before acknowledgement was received.

An `I_STR` can also fail while waiting for an acknowledgement if a message indicating an error or a hangup is received at the `STREAM` head. In addition, an error code can be returned in the positive or negative acknowledgement message, in the event the `ioctl()` command sent downstream fails. For these cases, `I_STR` shall fail with `errno` set to the value in the message.

`I_SWROPT` Sets the write mode using the value of the argument `arg`.

Valid bit settings for `arg` are:

`SNDZERO` Send a zero-length message downstream when a `write()` of 0 bytes occurs. To not send a zero-length message when a `write()` of 0 bytes occurs, the application shall ensure that this bit is not set in `arg` (for example, `arg` would be set to 0).

The `ioctl()` function with the `I_SWROPT` command shall fail if:

`EINVAL` `arg` is not the above value.

`I_GWROPT` Returns the current write mode setting, as described above, in the `int` that is pointed to by the argument `arg`.

`I_SENDFD` Creates a new reference to the open file description associated with the file descriptor `arg`, and writes a message on the `STREAMS`-based pipe fildes containing this reference, together with the user ID and group ID of the calling process.

The `ioctl()` function with the `I_SENDFD` command shall fail

if:

EAGAIN The sending STREAM is unable to allocate a message block to contain the file pointer; or the read queue of the receiving STREAM head is full and cannot accept the message sent by `I_SENDFD`.

EBADF The `arg` argument is not a valid, open file descriptor.

EINVAL The `fd` argument is not connected to a STREAM pipe.

ENXIO Hangup received on `fd`.

The `ioctl()` function with the `I_SENDFD` command may fail if:

EINVAL The `arg` argument is equal to the `fd` argument.

I_RECVFD Retrieves the reference to an open file description from a message written to a STREAMS-based pipe using the `I_SENDFD` command, and allocates a new file descriptor in the calling process that refers to this open file description. The `arg` argument is a pointer to a `strrecvfd` data structure as defined in `<stropts.h>`.

The `fd` member is a file descriptor. The `uid` and `gid` members are the effective user ID and effective group ID, respectively, of the sending process.

If `O_NONBLOCK` is not set, `I_RECVFD` shall block until a message is present at the STREAM head. If `O_NONBLOCK` is set, `I_RECVFD` shall fail with `errno` set to `[EAGAIN]` if no message is present at the STREAM head.

If the message at the STREAM head is a message sent by an `I_SENDFD`, a new file descriptor shall be allocated for the open file descriptor referenced in the message. The new file descriptor is placed in the `fd` member of the `strrecvfd` structure pointed to by `arg`.

The `ioctl()` function with the `I_RECVFD` command shall fail if:

EAGAIN A message is not present at the STREAM head read

queue and the O_NONBLOCK flag is set.

EBADMSG

The message at the STREAM head read queue is not a message containing a passed file descriptor.

EMFILE All file descriptors available to the process are currently open.

ENXIO Hangup received on fildes.

I_LIST Allows the process to list all the module names on the STREAM, up to and including the topmost driver name. If arg is a null pointer, the return value shall be the number of modules, including the driver, that are on the STREAM pointed to by fildes. This lets the process allocate enough space for the module names. Otherwise, it should point to a str_list structure.

The sl_nmods member indicates the number of entries the process has allocated in the array. Upon return, the sl_modlist member of the str_list structure shall contain the list of module names, and the number of entries that have been filled into the sl_modlist array is found in the sl_nmods member (the number includes the number of modules including the driver). The return value from ioctl() shall be 0. The entries are filled in starting at the top of the STREAM and continuing downstream until either the end of the STREAM is reached, or the number of requested modules (sl_nmods) is satisfied.

The ioctl() function with the I_LIST command shall fail if:

EINVAL The sl_nmods member is less than 1.

EAGAIN or ENOSR

Unable to allocate buffers.

I_ATMARK Allows the process to see if the message at the head of the STREAM head read queue is marked by some module downstream. The arg argument determines how the checking is done when there may be multiple marked messages on the STREAM head

read queue. It may take on the following values:

ANYMARK Check if the message is marked.

LASTMARK Check if the message is the last one marked on the queue.

The bitwise-inclusive OR of the flags ANYMARK and LASTMARK is permitted.

The return value shall be 1 if the mark condition is satisfied; otherwise, the value shall be 0.

The ioctl() function with the I_ATMARK command shall fail if:

EINVAL Invalid arg value.

I_CKBAND Checks if the message of a given priority band exists on the STREAM head read queue. This shall return 1 if a message of the given priority exists, 0 if no such message exists, or -1 on error. arg should be of type int.

The ioctl() function with the I_CKBAND command shall fail if:

EINVAL Invalid arg value.

I_GETBAND Returns the priority band of the first message on the STREAM head read queue in the integer referenced by arg.

The ioctl() function with the I_GETBAND command shall fail if:

ENODATA

No message on the STREAM head read queue.

I_CANPUT Checks if a certain band is writable. arg is set to the priority band in question. The return value shall be 0 if the band is flow-controlled, 1 if the band is writable, or -1 on error.

The ioctl() function with the I_CANPUT command shall fail if:

EINVAL Invalid arg value.

I_SETCLTIME This request allows the process to set the time the STREAM head shall delay when a STREAM is closing and there is data

on the write queues. Before closing each module or driver, if there is data on its write queue, the STREAM head shall delay for the specified amount of time to allow the data to drain. If, after the delay, data is still present, it shall be flushed. The `arg` argument is a pointer to an integer specifying the number of milliseconds to delay, rounded up to the nearest valid value. If `I_SETCLTIME` is not performed on a STREAM, an implementation-defined default timeout interval is used.

The `ioctl()` function with the `I_SETCLTIME` command shall fail if:

`EINVAL` Invalid `arg` value.

`I_GETCLTIME` Returns the close time delay in the integer pointed to by `arg`.

Multiplexed STREAMS Configurations

The following commands are used for connecting and disconnecting multiplexed STREAMS configurations. These commands use an implementation-defined default timeout interval.

`I_LINK` Connects two STREAMs, where `fildev` is the file descriptor of the STREAM connected to the multiplexing driver, and `arg` is the file descriptor of the STREAM connected to another driver. The STREAM designated by `arg` is connected below the multiplexing driver. `I_LINK` requires the multiplexing driver to send an acknowledgement message to the STREAM head regarding the connection. This call shall return a multiplexer ID number (an identifier used to disconnect the multiplexer; see `I_UNLINK`) on success, and -1 on failure.

The `ioctl()` function with the `I_LINK` command shall fail if:

`ENXIO` Hangup received on `fildev`.

`ETIME` Timeout before acknowledgement message was received at STREAM head.

`EAGAIN` or `ENOSR`

Unable to allocate STREAMS storage to perform the

I_LINK.

EBADF The `arg` argument is not a valid, open file descriptor.

EINVAL The `fildev` argument does not support multiplexing; or `arg` is not a STREAM or is already connected downstream from a multiplexer; or the specified I_LINK operation would connect the STREAM head in more than one place in the multiplexed STREAM.

An I_LINK can also fail while waiting for the multiplexing driver to acknowledge the request, if a message indicating an error or a hangup is received at the STREAM head of `fildev`. In addition, an error code can be returned in the positive or negative acknowledgement message. For these cases, I_LINK fails with `errno` set to the value in the message.

I_UNLINK Disconnects the two STREAMs specified by `fildev` and `arg`.

`fildev` is the file descriptor of the STREAM connected to the multiplexing driver. The `arg` argument is the multiplexer ID number that was returned by the I_LINK `ioctl()` command when a STREAM was connected downstream from the multiplexing driver. If `arg` is MUXID_ALL, then all STREAMs that were connected to `fildev` shall be disconnected. As in I_LINK, this command requires acknowledgement.

The `ioctl()` function with the I_UNLINK command shall fail if:

ENXIO Hangup received on `fildev`.

ETIME Timeout before acknowledgement message was received at STREAM head.

EAGAIN or ENOSR

Unable to allocate buffers for the acknowledgement message.

EINVAL Invalid multiplexer ID number.

An I_UNLINK can also fail while waiting for the multiplex?

ing driver to acknowledge the request if a message indicat?
ing an error or a hangup is received at the STREAM head of
fildes. In addition, an error code can be returned in the
positive or negative acknowledgement message. For these
cases, I_UNLINK shall fail with errno set to the value in
the message.

I_PLINK Creates a persistent connection between two STREAMs, where
fildes is the file descriptor of the STREAM connected to
the multiplexing driver, and arg is the file descriptor of
the STREAM connected to another driver. This call shall
create a persistent connection which can exist even if the
file descriptor fildes associated with the upper STREAM to
the multiplexing driver is closed. The STREAM designated
by arg gets connected via a persistent connection below the
multiplexing driver. I_PLINK requires the multiplexing
driver to send an acknowledgement message to the STREAM
head. This call shall return a multiplexer ID number (an
identifier that may be used to disconnect the multiplexer;
see I_PUNLINK) on success, and -1 on failure.

The ioctl() function with the I_PLINK command shall fail
if:

ENXIO Hangup received on fildes.

ETIME Timeout before acknowledgement message was received
at STREAM head.

EAGAIN or ENOSR

Unable to allocate STREAMS storage to perform the
I_PLINK.

EBADF The arg argument is not a valid, open file descrip?
tor.

EINVAL The fildes argument does not support multiplexing;
or arg is not a STREAM or is already connected down?
stream from a multiplexer; or the specified I_PLINK
operation would connect the STREAM head in more than

one place in the multiplexed STREAM.

An I_PLINK can also fail while waiting for the multiplexing driver to acknowledge the request, if a message indicating an error or a hangup is received at the STREAM head of fildes. In addition, an error code can be returned in the positive or negative acknowledgement message. For these cases, I_PLINK shall fail with errno set to the value in the message.

I_PUNLINK Disconnects the two STREAMs specified by fildes and arg from a persistent connection. The fildes argument is the file descriptor of the STREAM connected to the multiplexing driver. The arg argument is the multiplexer ID number that was returned by the I_PLINK ioctl() command when a STREAM was connected downstream from the multiplexing driver. If arg is MUXID_ALL, then all STREAMs which are persistent connections to fildes shall be disconnected. As in I_PLINK, this command requires the multiplexing driver to acknowledge the request.

The ioctl() function with the I_PUNLINK command shall fail if:

ENXIO Hangup received on fildes.

ETIME Timeout before acknowledgement message was received at STREAM head.

EAGAIN or ENOSR

Unable to allocate buffers for the acknowledgement message.

EINVAL Invalid multiplexer ID number.

An I_PUNLINK can also fail while waiting for the multiplexing driver to acknowledge the request if a message indicating an error or a hangup is received at the STREAM head of fildes. In addition, an error code can be returned in the positive or negative acknowledgement message. For these cases, I_PUNLINK shall fail with errno set to the value in

the message.

RETURN VALUE

Upon successful completion, `ioctl()` shall return a value other than `-1` that depends upon the STREAMS device control function. Otherwise, it shall return `-1` and set `errno` to indicate the error.

ERRORS

Under the following general conditions, `ioctl()` shall fail if:

EBADF The `fildev` argument is not a valid open file descriptor.

EINTR A signal was caught during the `ioctl()` operation.

EINVAL The STREAM or multiplexer referenced by `fildev` is linked (directly or indirectly) downstream from a multiplexer.

If an underlying device driver detects an error, then `ioctl()` shall fail if:

EINVAL The request or `arg` argument is not valid for this device.

EIO Some physical I/O error has occurred.

ENOTTY The file associated with the `fildev` argument is not a STREAMS device that accepts control functions.

ENXIO The request and `arg` arguments are valid for this device driver, but the service requested cannot be performed on this particular sub-device.

ENODEV The `fildev` argument refers to a valid STREAMS device, but the corresponding device driver does not support the `ioctl()` function.

If a STREAM is connected downstream from a multiplexer, any `ioctl()` command except `I_UNLINK` and `I_PUNLINK` shall set `errno` to `[EINVAL]`.

The following sections are informative.

EXAMPLES

None.

APPLICATION USAGE

The implementation-defined timeout interval for STREAMS has historically been 15 seconds.

RATIONALE

None.

FUTURE DIRECTIONS

The `ioctl()` function may be removed in a future version.

SEE ALSO

Section 2.6, STREAMS, `close()`, `fcntl()`, `getmsg()`, `open()`, `pipe()`, `poll()`, `putmsg()`, `read()`, `sigaction()`, `write()`

The Base Definitions volume of POSIX.1-2017, `<stropts.h>`

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