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## Red Hat Enterprise Linux Release 9.2 Manual Pages on 'sem\_post.3' command

## \$ man sem\_post.3

SEM\_POST(3)

Linux Programmer's Manual

SEM\_POST(3)

NAME

sem\_post - unlock a semaphore

### **SYNOPSIS**

#include <semaphore.h>

int sem\_post(sem\_t \*sem);

Link with -pthread.

## **DESCRIPTION**

sem\_post() increments (unlocks) the semaphore pointed to by sem. If the semaphore's value consequently becomes greater than zero, then an? other process or thread blocked in a sem\_wait(3) call will be woken up and proceed to lock the semaphore.

### **RETURN VALUE**

sem\_post() returns 0 on success; on error, the value of the semaphore is left unchanged, -1 is returned, and errno is set to indicate the er? ror.

#### **ERRORS**

EINVAL sem is not a valid semaphore.

## **EOVERFLOW**

The maximum allowable value for a semaphore would be exceeded.

# **ATTRIBUTES**

For an explanation of the terms used in this section, see at? tributes(7).

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?Interface ? Attribute ? Value ?

?????????????????????????????????????

?sem\_post()? Thread safety? MT-Safe?

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### **CONFORMING TO**

POSIX.1-2001.

## **NOTES**

sem\_post() is async-signal-safe: it may be safely called within a sig? nal handler.

## **EXAMPLES**

See sem\_wait(3) and shm\_open(3).

### SEE ALSO

sem\_getvalue(3), sem\_wait(3), sem\_overview(7), signal-safety(7)

### **COLOPHON**

This page is part of release 5.10 of the Linux man-pages project. A description of the project, information about reporting bugs, and the latest version of this page, can be found at https://www.kernel.org/doc/man-pages/.

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