



## **Red Hat Enterprise Linux Release 9.2 Manual Pages on 'timer\_getoverrun.3p' command**

**\$ man timer\_getoverrun.3p**

TIMER\_GETOVERRUN(3P) POSIX Programmer's Manual TIMER\_GETOVERRUN(3P)

### PROLOG

This manual page is part of the POSIX Programmer's Manual. The Linux implementation of this interface may differ (consult the corresponding Linux manual page for details of Linux behavior), or the interface may not be implemented on Linux.

### NAME

timer\_getoverrun, timer\_gettime, timer\_settime ? per-process timers

### SYNOPSIS

```
#include <time.h>

int timer_getoverrun(timer_t timerid);

int timer_gettime(timer_t timerid, struct itimerspec *value);

int timer_settime(timer_t timerid, int flags,
    const struct itimerspec *restrict value,
    struct itimerspec *restrict ovalue);
```

### DESCRIPTION

The timer\_gettime() function shall store the amount of time until the specified timer, timerid, expires and the reload value of the timer into the space pointed to by the value argument. The it\_value member of this structure shall contain the amount of time before the timer expires, or zero if the timer is disarmed. This value is returned as the interval until timer expiration, even if the timer was armed with absolute time. The it\_interval member of value shall contain the reload

value last set by `timer_settime()`.

The `timer_settime()` function shall set the time until the next expiration of the timer specified by `timerid` from the `it_value` member of the `value` argument and arm the timer if the `it_value` member of `value` is non-zero. If the specified timer was already armed when `timer_settime()` is called, this call shall reset the time until next expiration to the value specified. If the `it_value` member of `value` is zero, the timer shall be disarmed. The effect of disarming or resetting a timer with pending expiration notifications is unspecified.

If the flag `TIMER_ABSTIME` is not set in the argument `flags`, `timer_settime()` shall behave as if the time until next expiration is set to be equal to the interval specified by the `it_value` member of `value`. That is, the timer shall expire in `it_value` nanoseconds from when the call is made. If the flag `TIMER_ABSTIME` is set in the argument `flags`, `timer_settime()` shall behave as if the time until next expiration is set to be equal to the difference between the absolute time specified by the `it_value` member of `value` and the current value of the clock associated with `timerid`. That is, the timer shall expire when the clock reaches the value specified by the `it_value` member of `value`. If the specified time has already passed, the function shall succeed and the expiration notification shall be made.

The `reload` value of the timer shall be set to the value specified by the `it_interval` member of `value`. When a timer is armed with a non-zero `it_interval`, a periodic (or repetitive) timer is specified.

Time values that are between two consecutive non-negative integer multiples of the resolution of the specified timer shall be rounded up to the larger multiple of the resolution. Quantization error shall not cause the timer to expire earlier than the rounded time value.

If the argument `ovalue` is not `NULL`, the `timer_settime()` function shall store, in the location referenced by `ovalue`, a value representing the previous amount of time before the timer would have expired, or zero if the timer was disarmed, together with the previous timer reload value.

Timers shall not expire before their scheduled time.

Only a single signal shall be queued to the process for a given timer at any point in time. When a timer for which a signal is still pending expires, no signal shall be queued, and a timer overrun shall occur. When a timer expiration signal is delivered to or accepted by a process, the `timer_getoverrun()` function shall return the timer expiration overrun count for the specified timer. The overrun count returned contains the number of extra timer expirations that occurred between the time the signal was generated (queued) and when it was delivered or accepted, up to but not including an implementation-defined maximum of `{DELAYTIMER_MAX}`. If the number of such extra expirations is greater than or equal to `{DELAYTIMER_MAX}`, then the overrun count shall be set to `{DELAYTIMER_MAX}`. The value returned by `timer_getoverrun()` shall apply to the most recent expiration signal delivery or acceptance for the timer. If no expiration signal has been delivered for the timer, the return value of `timer_getoverrun()` is unspecified.

The behavior is undefined if the value specified by the `timerid` argument to `timer_getoverrun()`, `timer_gettime()`, or `timer_settime()` does not correspond to a timer ID returned by `timer_create()` but not yet deleted by `timer_delete()`.

## RETURN VALUE

If the `timer_getoverrun()` function succeeds, it shall return the timer expiration overrun count as explained above.

If the `timer_gettime()` or `timer_settime()` functions succeed, a value of 0 shall be returned.

If an error occurs for any of these functions, the value -1 shall be returned, and `errno` set to indicate the error.

## ERRORS

The `timer_settime()` function shall fail if:

**EINVAL** A value structure specified a nanosecond value less than zero or greater than or equal to 1000 million, and the `it_value` member of that structure did not specify zero seconds and nanoseconds.

The `timer_settime()` function may fail if:

**EINVAL** The `it_interval` member of value is not zero and the timer was

created with notification by creation of a new thread (sigev\_sigev\_notify was SIGEV\_THREAD) and a fixed stack address has been set in the thread attribute pointed to by sigev\_notify\_attributes.

The following sections are informative.

## EXAMPLES

None.

## APPLICATION USAGE

Using fixed stack addresses is problematic when timer expiration is signaled by the creation of a new thread. Since it cannot be assumed that the thread created for one expiration is finished before the next expiration of the timer, it could happen that two threads use the same memory as a stack at the same time. This is invalid and produces undefined results.

## RATIONALE

Practical clocks tick at a finite rate, with rates of 100 hertz and 1000 hertz being common. The inverse of this tick rate is the clock resolution, also called the clock granularity, which in either case is expressed as a time duration, being 10 milliseconds and 1 millisecond respectively for these common rates. The granularity of practical clocks implies that if one reads a given clock twice in rapid succession, one may get the same time value twice; and that timers must wait for the next clock tick after the theoretical expiration time, to ensure that a timer never returns too soon. Note also that the granularity of the clock may be significantly coarser than the resolution of the data format used to set and get time and interval values. Also note that some implementations may choose to adjust time and/or interval values to exactly match the ticks of the underlying clock.

This volume of POSIX.1-2017 defines functions that allow an application to determine the implementation-supported resolution for the clocks and requires an implementation to document the resolution supported for timers and nanosleep() if they differ from the supported clock resolution. This is more of a procurement issue than a runtime application

issue.

If an implementation detects that the value specified by the `timerid` argument to `timer_getoverrun()`, `timer_gettime()`, or `timer_settime()` does not correspond to a timer ID returned by `timer_create()` but not yet deleted by `timer_delete()`, it is recommended that the function should fail and report an [EINVAL] error.

#### FUTURE DIRECTIONS

None.

#### SEE ALSO

`clock_getres()`, `timer_create()`

The Base Definitions volume of POSIX.1-2017, `<time.h>`

#### COPYRIGHT

Portions of this text are reprinted and reproduced in electronic form from IEEE Std 1003.1-2017, Standard for Information Technology -- Portable Operating System Interface (POSIX), The Open Group Base Specifications Issue 7, 2018 Edition, Copyright (C) 2018 by the Institute of Electrical and Electronics Engineers, Inc and The Open Group. In the event of any discrepancy between this version and the original IEEE and The Open Group Standard, the original IEEE and The Open Group Standard is the referee document. The original Standard can be obtained online at <http://www.opengroup.org/unix/online.html>.

Any typographical or formatting errors that appear in this page are most likely to have been introduced during the conversion of the source files to man page format. To report such errors, see [https://www.kernel.org/doc/man-pages/reporting\\_bugs.html](https://www.kernel.org/doc/man-pages/reporting_bugs.html).